



OMRON CORPORATION
ELECTRONIC AND MECHANICAL
COMPONENTS COMPANY



OKAOTM Vision

Result Stabilization V1.1

Software Library

Software Specification Document

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■ Revision History

Date	Rev	Contents	Prepared by	Reviewed by	Approved by
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■ Additional Notes

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1 Outline of Library

The Result Stabilization V1.1 Software Library (hereafter referred to as “This Library”) stabilizes the result of number of object person/people, age, gender and face recognition based on the result of Human Body Detection, Face Detection, Age/Gender Estimation and Face Recognition in each frame output in chronological order. This Library has three functions as below.

(1) Result Stabilizing Function

For example, the OMRON supplying image processing module-HVC outputs detecting result of every frame. This also does for the result with lower confidence like the object facing sideways or taken under bad shooting condition. This Library uses the results with more confidence in the numbers of frames to get the final result of age/gender estimation and face recognition. It also stabilizes Expression Estimation, Gaze Estimation, Blink Estimation and Face Direction Estimation results with previous frames and their confidence.

This result stabilizing process refers maximum 20 previous frames (includes current frame).

(2) Tracking Function

To deliver function above, This Library tracks detecting result of previous and current frames to see whether the people in both frames are the same or not (tracking) and gives ID (tracking ID) for the ones qualified as the same ones. This Library tracks for each Human Body Detection and Face Detection.

(3) Rectangle Steadiness Function

Outputs steadied size and positional information on each frame.

2 Software Specifications

2.1 Library Usage

To use This Library, STBAPI.h, STBCommonDef.h, STBTypedef.h should be added to the include path of the application.

2.2 Error Code Definitions

Error Code	Description	Value
STB_NORMAL	Normal end	0
STB_ERR_INITIALIZE	Initializing Error	-2
STB_ERR_INVALIDPARAM	Parameter Error	-3
STB_ERR_NOHANDLE	Handle Error	-7
STB_ERR_PROCESSCONDITION	Processing condition Error	-8

2.3 Function List

Function name	Summary	page
STB_GetVersion	Get version	9
STB_CreateHandle	Create stabilization handle	9
STB_DeleteHandle	Delete stabilization handle	9
STB_SetFrameResult	Set frame result	10
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STB_GetFaces	Get stabilized face data	12
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STB_SetTrSteadinessParam	Set rectangle steadiness parameter	14
STB_GetTrSteadinessParam	Get rectangle steadiness parameter	14
STB_SetPeThresholdUse	Set estimation result stabilizing threshold value	15
STB_GetPeThresholdUse	Get estimation result stabilizing threshold value	15
STB_SetPeAngleUse	Set estimation result stabilizing angle	16
STB_GetPeAngleUse	Get estimation result stabilizing angle	16
STB_SetPeCompleteFrameCount	Set age/gender estimation complete frame count	17
STB_GetPeCompleteFrameCount	Get age/gender estimation complete frame count	17
STB_SetFrThresholdUse	Set recognition stabilizing threshold value	18
STB_GetFrThresholdUse	Get recognition stabilizing threshold value	18
STB_SetFrAngleUse	Set recognition stabilizing angle	19
STB_GetFrAngleUse	Get recognition stabilizing angle	19
STB_SetFrCompleteFrameCount	Set recognition stabilizing complete frame count	20
STB_GetFrCompleteFrameCount	Get recognition stabilizing complete frame count	20
STB_SetFrMinRatio	Set recognition minimum account ratio	21
STB_GetFrMinRatio	Get recognition minimum account ratio	21

2.4 Processing Sequence

An example of the sequence to use This Library as below.

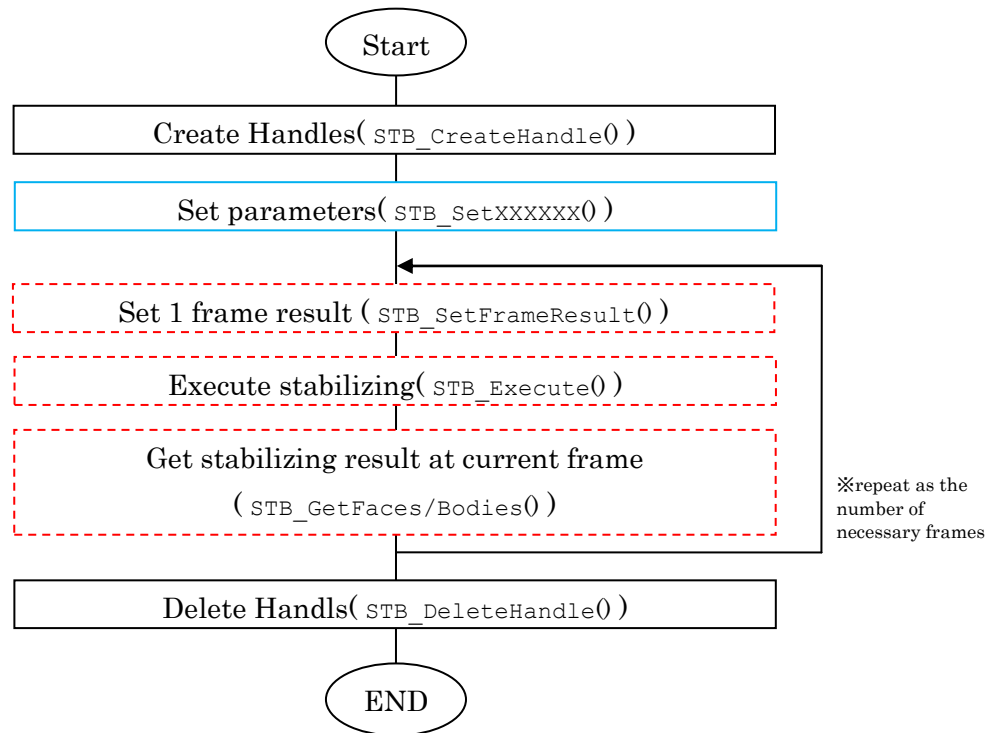


Figure 1 Processing sequence example

- Process executing to use This Library
- Process executing as needed
- Process required for each frame detection/estimation result

2.5 Stabilization Status

This Library outputs stabilization status.

The result information status of **Age/Gender Estimation** and **Face recognition** for a person shifts as No Data→Calculating→Complete→Fixed.

This “No Data/Calculating/Complete/Fixed” will be shown at “status”.

For **Expression Estimation**, **Gaze Estimation**, **Blink Estimation** and **Face Direction Estimation** will be done the stabilizing process, they won't get to the Complete status to see real-time change. The status will shift to No Data to Calculating.

●Stabilizing Status Definition

One of those items below will be output for Stabilizing Status.

STB_STATUS_NO_DATA	No Data	: No data of this person
STB_STATUS_CALCULATING	Calculating	: Not enough data of this person
STB_STATUS_COMPLETE	Complete	: Stabilization process completed
STB_STATUS_FIXED	Fixed	: Stabilization result has fixed

2.6 Function Specifications

●Get Version

```
STB_INT32 STB_GetVersion(STB_INT8 *pnMajorVersion, STB_INT8 *pnMinorVersion)
```

Arguments	Output : pnMajorVersion pnMinorVersion	Major Version Minor Version
Return values	STB_NORMAL STB_ERR_INVALIDPARAM	Normal end Parameter Error -NULL pointer argument
Description	Gets this Library's version	

●Create/Delete Stabilization handle

```
HSTB STB_CreateHandle(STB_UINT32 unUseFuncFlag)
```

Arguments	unUseFuncFlag	Flag
Return values	not NULL NULL	Stabilization handle Failure -insufficient Backup memory -inadequate effectiveness flag
Description	<p>Creates the Stabilization handle.</p> <p>Specify the stabilizing function at unUseFuncFlag. Each function is allocated as bit numbers. Set 1 for executing bit, 0 for not executing bit, or “ ” to stabilize multiple functions.</p> <p>The defined value for each functions are as follows:</p> <pre>#define STB_FUNC_BD (0x00000001U) /* [LSB]bit0: Body Tracking */ #define STB_FUNC_DT (0x00000004U) /* [LSB]bit2: Face Tracking */ #define STB_FUNC_PT (0x00000008U) /* [LSB]bit3: Face Direction */ #define STB_FUNC_AG (0x00000010U) /* [LSB]bit4: Age Estimation */ #define STB_FUNC_GN (0x00000020U) /* [LSB]bit5: Gender Estimation */ #define STB_FUNC_GZ (0x00000040U) /* [LSB]bit6: Gaze Estimation */ #define STB_FUNC_BL (0x00000080U) /* [LSB]bit7: Blink Estimation */ #define STB_FUNC_EX (0x00000100U) /* [MSB]bit0: Expression Estimation */ #define STB_FUNC_FR (0x00000200U) /* [MSB]bit1: Face Recognition */</pre> <p><u>Activate face detection(STB_FUNC_DT) and face direction estimation(STB_FUNC_PT) to stabilize age/gender/gaze/blink/expression estimation and face recognition result.</u></p> <p>* Call STB_DeleteHandle() to delete the handle after use.</p>	

```
VOID STB_DeleteHandle(HSTB hSTB)
```

Arguments	Input : hSTB	Stabilization handle
Return values	None	
Description	Deletes the handle created at STB_CreateHandle().	

- Set frame result

[illegible]

Arguments	Input : hSTB stFrameResult	Stabilization handle Result information frame
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	<p>Stores detection/estimation information on Stabilization handle.</p> <p><u>Set the information of face central coordinate, size and direction to stabilize age/gender/gaze/blink/expression estimation and face recognition.</u></p> <p>Refer 2.7 Struct Definition for input data format of [STB_FRAME_RESULT].</p>	
Input specifications	<pre> stFrameResult.bodys.nCount : 0~35 stFrameResult.bodys.body[*].center.nX : 0~8191 stFrameResult.bodys.body[*].center.nY : 0~8191 stFrameResult.bodys.body[*].nSize : 20~8192 stFrameResult.bodys.body[*].nConfidence : 0~1000 stFrameResult.faces.nCount : 0~35 stFrameResult.faces.face[*].center.nX : 0~8191 stFrameResult.faces.face[*].center.nY : 0~8191 stFrameResult.faces.face[*].nSize : 20~8192 stFrameResult.faces.face[*].nConfidence : 0~1000 stFrameResult.faces.face[*].direction.nLR : -180~179 stFrameResult.faces.face[*].direction.nUD : -180~179 stFrameResult.faces.face[*].direction.nRoll : -180~179 stFrameResult.faces.face[*].direction.nConfidence : 0~1000 stFrameResult.faces.face[*].age.nAge : 0~75, -128(not estimable) stFrameResult.faces.face[*].age.nConfidence : 0~1000, -128(not estimable) stFrameResult.faces.face[*].gender.nGender : 0(Female), 1(Male), -128(not estimable) stFrameResult.faces.face[*].gender.nConfidence : 0~1000, -128(not estimable) stFrameResult.faces.face[*].gaze.nLR : -90~90, -128(not estimable) stFrameResult.faces.face[*].gaze.nUD : -90~90, -128(not estimable) stFrameResult.faces.face[*].blink.nLeftEye : 1~1000, -128(not estimable) stFrameResult.faces.face[*].blink.nRightEye : 1~1000, -128(not estimable) stFrameResult.faces.face[*].expression.anScore[STB_Expression_Max] : 0~100, -128(not estimable) stFrameResult.faces.face[*].expression.nDegree : -100~100, -128(not estimable) stFrameResult.faces.face[*].recognition.nUID : 0~499, -1(ID not available), -127(not registered), -128(not estimable) stFrameResult.faces.face[*].recognition.nScore : 0~1000, -127(not registered), -128(not estimable) </pre>	

●Clear frame result

STB_INT32 STB_ClearFrameResults(HSTB hSTB)

Arguments	Input : hSTB	Stabilization handle
Return values	STB_NORMAL STB_ERR_NOHANDLE	Normal end Handle error -improper handle content
Description	<p>Clears all the previous saved data.</p> <p>* Executing this function will not delete parameters set at setting functions.</p> <p>Personal ID output at STB_GetFaces() and STB_GetBodies() will start from “0” after STB_ClearFrameResults().</p>	

●Execute stabilizing process

STB_INT32 STB_Execute(HSTB hSTB)

Arguments	Input : hSTB	Stabilization handle
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INITIALIZE STB_ERR_INVALIDPARAM STB_ERR_PROCESSCONDITION	Normal end Handle error -improper handle content Initial error -no result information Parameter error Processing Condition error -over maximum number of tracking targets
Description	<p>Converts into stabilized result with set previous frame data.</p> <p>Stabilization has those tracking function, rectangle steadiness function and result stabilizing function.</p> <p>- Tracking Function Calculates as the same person by allocating ID for face and human body detecting rectangle.</p> <p>- Rectangle Steadiness Function Steadies face and human body detecting rectangle.</p> <p>- Estimation Result Stabilization Function Stabilizes results of age/gender/gaze/blink/expression/face direction estimation and face recognition.</p>	

●Get stabilized result

```
STB_INT32 STB_GetFaces (HSTB hSTB, STB_UINT32 *punFaceCount, STB_FACE stFace[])
```

Arguments	Input : hSTB Output : pnFaceCount stFaces	Stabilization handle Number of stabilized faces Stabilized face data
Return Values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INITIALIZE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Initial error -no stabilization Parameter error
Description	Gets stabilized face data. The data will be output in order of tracking ID. Refer 2.7 Struct Definition for output data format of [STB_FACE].	

```
STB_INT32 STB_GetBodies (HSTB hSTB, STB_UINT32 *punBodyCount,  
                         STB_BODY stBody[])
```

Arguments	Input : hSTB Output : pnBodyCount stBody	Stabilization handle Number of stabilized bodies Stabilized body data
Return Values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INITIALIZE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Initial error -no stabilization Parameter error
Description	Gets stabilized body data. The data will be output in order of tracking ID. Refer 2.7 Struct Definition for output data format of [STB_BODY].	

●Set/Get maximum retry count

STB_INT32 STB_SetTrRetryCount (HSTB hSTB, STB_INT32 nMaxRetryCount)

Arguments	Input : hSTB nMaxRetryCount	Stabilization handle Maximum retry count
Return Values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	Sets the maximum retry count. Set the number of maximum retry when not finding a face/human body while tracking. Terminates tracking as lost object when keeps failing for this maximum retry count.	
Input specifications	nMaxRetryCount : 0 to 300	
Default value	nMaxRetryCount =2	

STB_INT32 STB_GetTrRetryCount (HSTB hSTB, STB_INT32 *pnMaxRetryCount)

Arguments	Input : hSTB Output : pnMaxRetryCount	Stabilization handle Maximum retry count
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set maximum retry count.	

●Set/Get rectangle steadiness parameter

STB_INT32 STB_SetTrSteadinessParam

(HSTB hSTB, STB_INT32 nPosSteadinessParam, STB_INT32 nSizeSteadinessParam)

Arguments	Input : hSTB nPosSteadinessParam nSizeSteadinessParam	Stabilization handle Rectangle position steadiness parameter Rectangle size steadiness parameter
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	Sets steadiness parameter of position and size. - nPosSteadinessParam For example, outputs the previous position coordinate data if the shifting measure is within 30%, existing position coordinate data if it has shift more than 30% when the rectangle position steadiness parameter has set as initial value of 30. - nSizeSteadinessParam For example, outputs the previous detecting size data if the changing measure is within 30%, existing size data if it has changed more than 30% when the rectangle size steadiness parameter has set as initial value of 30.	
Input specifications	nPosSteadinessParam : 0 to 100 nSizeSteadinessParam : 0 to 100	
Default value	nPosSteadinessParam = 30 nSizeSteadinessParam = 30	

STB_INT32 STB_GetTrSteadinessParam(HSTB hSTB,

STB_INT32 *pnPosSteadinessParam, STB_INT32 *pnSizeSteadinessParam)

Arguments	Input : hSTB Output: pnPosSteadinessParam pnSizeSteadinessParam	Stabilization handle Rectangle position steadiness parameter Rectangle size steadiness parameter
Return Values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set steadiness parameter of position and size.	

●Set/Get estimation result stabilizing threshold value

STB_INT32 STB_SetPeThresholdUse (HSTB hSTB, STB_INT32 nThreshold)

Arguments	Input : hSTB nThreshold	Stabilization handle Face direction confidence threshold value
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	<p>Sets the stabilizing threshold value of Face direction confidence.</p> <p><u>* This is for the six functions of age, gender, gaze, blink, expression and face direction estimation functions.</u></p> <p>Eliminates face data with lower confidence than the value set at this function for accuracy improvement of result stabilizing.</p> <p>For example, the previous data confidence with below 500 will not be applied for stabilizing when the face direction confidence threshold value has set as 500.</p>	
Input specifications	nThreshold : 0 to 1000	
Default value	nThreshold = 300	

STB_INT32 STB_GetPeThresholdUse (HSTB hSTB, STB_INT32 *pnThreshold)

Arguments	Input : hSTB Output : pnThreshold	Stabilization handle Face direction confidence threshold value
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set threshold value of Face direction confidence.	

●Set/Get estimation result stabilizing angle

```
STB_INT32 STB_SetPeAngleUse (HSTB hSTB, STB_INT32 nMinUDAngle,
                             STB_INT32 nMaxUDAngle, STB_INT32 nMinLRAngle, STB_INT32 nMaxLRAngle)
```

Arguments	Input : hSTB nMinUDAngle nMaxUDAngle nMinLRAngle nMaxLRAngle	Stabilization handle Minimum up-down angle of the face Maximum up-down angle of the face Minimum left-right angle of the face Maximum left-right angle of the face
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	<p>Sets angle threshold value of Face direction. <u>* This is for the six functions of age, gender, gaze, blink, expression and face direction estimation functions.</u></p> <p>Eliminates face data with out of the set angle at this function for accuracy improvement of result stabilizing.</p> <p>For example, the previous data with up-down angle of below -16degree and over 21 degree will not be applied for stabilizing when the up-down angle threshold value of Face direction has set as 15 for minimum and 21 for maximum.</p>	
Input specifications	nMinUDAngle : -90 to 90 nMaxUDAngle : -90 to 90 nMinLRAngle : -90 to 90 nMaxLRAngle : -90 to 90 nMinUDAngle ≤ nMaxUDAngle nMinLRAngle ≤ nMaxLRAngle	
Default value	nMinUDAngle = -15 nMaxUDAngle = 20 nMinLRAngle = -30 nMaxLRAngle = 30	

```
STB_INT32 STB_GetPeAngleUse (HSTB hSTB, STB_INT32 *pnMinUDAngle,
                             STB_INT32 *pnMaxUDAngle, STB_INT32 *pnMinLRAngle, STB_INT32 *pnMaxLRAngle)
```

Arguments	Input : hSTB Output : pnMinUDAngle pnMaxUDAngle pnMinLRAngle pnMaxLRAngle	Stabilization handle Minimum up-down angle of the face Maximum up-down angle of the face Minimum left-right angle of the face Maximum left-right angle of the face
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set angle threshold value of Face direction.	

●Set/Get age/gender estimation complete frame count

STB_INT32 STB_SetPeCompleteFrameCount(HSTB hSTB, STB_INT32 nFrameCount)

Arguments	Input : hSTB nFrameCount	Stabilization handle The number of previous frames applying to fix the result
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	<p>Sets the number of previous frames applying to fix stabilization. <u>* This is for the two functions of age and gender estimation.</u></p> <p>The data used for stabilizing process (=averaging) is only the one fulfilled the STB_SetPeThresholdUse and STB_SetPeAngleUse condition. Stabilizing process will be completed with data more than the number of frames set at this function and it won't be done with less data.</p>	
Input specifications	nFrameCount : 1 to 20	
Default value	nFrameCount = 5	

STB_INT32 STB_GetPeCompleteFrameCount(HSTB hSTB, STB_INT32 *pnFrameCount)

Arguments	Input : hSTB Output : pnFrameCount	Stabilization handle The number of previous frames applying to fix the result
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set complete frame count.	

●Set/Get recognition stabilizing threshold value

STB_INT32 STB_SetFrThresholdUse (HSTB hSTB, STB_INT32 nThreshold)

Arguments	Input : hSTB nThreshold	Stabilization handle Face direction confidence threshold value
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	Sets stabilizing threshold value of Face direction confidence to improve recognition stabilization. Eliminates face data with lower confidence than the value set at this function. For example, the previous data confidence with below 500 will not be applied for stabilizing when the face direction confidence threshold value has set as 500.	
Input specifications	nThreshold : 0 to 1000	
Default value	nThreshold = 300	

STB_INT32 STB_GetFrThresholdUse (HSTB hSTB, STB_INT32 *pnThreshold)

Arguments	Input : hSTB Output : pnThreshold	Stabilization handle Face direction confidence threshold value
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set threshold value of Face direction confidence.	

●Set/Get recognition stabilizing angle

```
STB_INT32 STB_SetFrAngleUse (HSTB hSTB, STB_INT32 nMinUDAngle,
                             STB_INT32 nMaxUDAngle, STB_INT32 nMinLRAngle, STB_INT32 nMaxLRAngle)
```

Arguments	Input : hSTB nMinUDAngle nMaxUDAngle nMinLRAngle nMaxLRAngle	Stabilization handle Minimum up-down angle of the face Maximum up-down angle of the face Minimum left-right angle of the face Maximum left-right angle of the face
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	Sets angle threshold value of Face direction for accuracy improvement of recognition stabilizing. Eliminates face data with out of the set angle at this function. For example, the previous data with up-down angle of below -16degree and over 21 degree will not be applied for stabilizing when the up-down angle threshold value of Face direction has set as 15 for minimum and 21 for maximum.	
Input specifications	nMinUDAngle : -90 to 90 nMaxUDAngle : -90 to 90 nMinLRAngle : -90 to 90 nMaxLRAngle : -90 to 90 nMinUDAngle ≤ nMaxUDAngle nMinLRAngle ≤ nMaxLRAngle	
Default value	nMinUDAngle = -15 nMaxUDAngle = 20 nMinLRAngle = -30 nMaxLRAngle = 30	

```
STB_INT32 STB_GetFrAngleUse (HSTB hSTB, STB_INT32 *pnMinUDAngle,
                              STB_INT32 *pnMaxUDAngle, STB_INT32 *pnMinLRAngle, STB_INT32 *pnMaxLRAngle)
```

Arguments	Input : hSTB Output : pnMinUDAngle pnMaxUDAngle pnMinLRAngle pnMaxLRAngle	Stabilization handle Minimum up-down angle of the face Maximum up-down angle of the face Minimum left-right angle of the face Maximum left-right angle of the face
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set angle threshold value of Face direction.	

●Set/Get recognition stabilizing complete frame count

STB_INT32 STB_SetFrCompleteFrameCount (STB_HANDLE hSTB, STB_INT32 nFrameCount)

Arguments	Input : hSTB nFrameCount	Stabilization handle The number of previous frames applying to fix the result
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	Sets the number of previous frames applying to fix the recognition stabilizing. The data used for stabilizing process (=averaging) is only the one fulfilled the STB_SetFrThresholdUse and STB_SetFrAngleUse condition. Stabilizing process will be completed with a recognition ID fulfilled seizing ratio in result fixing frames and will not be done without one. * Refer STB_SetFrMinRatio function for account ratio function.	
Input specifications	nFrameCount : 0 to 20	
Default value	nFrameCount = 5	

STB_INT32 STB_GetFrCompleteFrameCount (STB_HANDLE hSTB,
STB_INT32 *pnFrameCount)

Arguments	Input : hSTB Output : pnFrameCount	Stabilization handle The number of previous frames applying to fix the result
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set complete frame count.	

●Set/Get recognition minimum account ratio

STB_INT32 STB_SetFrMinRatio(STB_HANDLE hSTB, STB_INT32 nMinRatio)

Arguments	Input : hSTB nMinRatio	Stabilization handle Recognition minimum account ratio
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error
Description	<p>Sets minimum account ratio in complete frame count for accuracy improvement of recognition stabilizing.</p> <p>For example, when there are 7 frames of extracted usable data in referred previous 20 frames, STB_SetFrCompleteFrameCount function has set “10” for the complete frame count and “60” for the recognition minimum account ratio. Creates frequency distribution of recognition result in the set 10 frames.</p> <p>Recognized as “Mr. A” (1 frame) Recognized as “Mr. B” (4 frames) Recognized as “Mr. C” (2 frames)</p> <p>In this case, the most account ratio “Mr. B” will be output as stabilized result. However, this recognition status will be output as “STB_STATUS_CALCULATING” since the account ratio is about 57%(= 4 frames/10 frames) , (Mr. B seizing ratio=) 57% < recognition account ratio (=60%).</p>	
Input specifications	nMinRatio : 0 to 100	
Default value	nMinRatio = 60	

STB_INT32 STB_GetFrMinRatio (STB_HANDLE hSTB, STB_INT32 *pnMinRatio)

Arguments	Input : hSTB Output : pnMinRatio	Stabilization handle Recognition minimum account ratio
Return values	STB_NORMAL STB_ERR_NOHANDLE STB_ERR_INVALIDPARAM	Normal end Handle error -improper handle content Parameter error -NULL pointer argument
Description	Gets the set recognition minimum account ratio.	

2.7 Struct Definitions

●Input result information

STB_FRAME_RESULT

Members	STB_FRAME_RESULT_BODYYS bodyys STB_FRAME_RESULT_FACES faces	Human body detection result Face detection result
Description	Input result information	

●Human body detection result information

STB_FRAME_RESULT_BODYYS

Members	STB_INT32 nCount STB_FRAME_RESULT_DETECTION body[35]	Detecting number Human body detection result detail
Description	Human body detection result information	

●Face detection result information

STB_FRAME_RESULT_FACES

Members	STB_INT32 nCount STB_FRAME_RESULT_FACE face[35]	Detecting number Face detection result detail
Description	Face detection result information	

●Human body detection result detail

STB_FRAME_RESULT_DETECTION

Members	STB_POINT center STB_INT32 nSize STB_INT32 nConfidence	Central coordinate Size Confidence
Description	Human body detection result detail	

●Face detection result detail

STB_FRAME_RESULT_FACE

Members	STB_POINT center STB_INT32 nSize STB_INT32 nConfidence STB_FRAME_RESULT_DIRECTION direction STB_FRAME_RESULT_AGE age STB_FRAME_RESULT_GENDER gender STB_FRAME_RESULT_GAZE gaze STB_FRAME_RESULT_BLINK blink STB_FRAME_RESULT_EXPRESSION expression STB_FRAME_RESULT_RECOGNITION recognition	Central coordinate Size Confidence Face direction estimation result Age estimation result Gender estimation result Gaze estimation result Blink estimation result Expression estimation result Face recognition result
Description	Face detection result detail	

●Coordinate

STB_POINT

Members	STB_INT32 nX STB_INT32 nY	X Coordinate Y Coordinate
Description	Coordinate	

●Face direction estimation result

STB_FRAME_RESULT_DIRECTION

Members	STB_INT32 nLR	Left-right angle
	STB_INT32 nUD	Up-down angle
	STB_INT32 nRoll	Roll angle
	STB_INT32 nConfidence	Confidence
Description	Face direction(Degree) estimation result	

●Age estimation result

STB_FRAME_RESULT_AGE

Members	STB_INT32 nAge	Age
	STB_INT32 nConfidence	Confidence
Description	Age estimation result	

●Gender estimation result

STB_FRAME_RESULT_GENDER

Members	STB_INT32 nGender	Gender
	STB_INT32 nConfidence	Confidence
Description	Gender estimation result	

●Gaze estimation result

STB_FRAME_RESULT_GAZE

Members	STB_INT32 nLR	Left-right angle
	STB_INT32 nUD	Up-down angle
Description	Gaze(Degree) estimation result	

●Blink estimation result

STB_FRAME_RESULT_BLINK

Members	STB_INT32 nLeftEye	Left eye score
	STB_INT32 nRightEye	Right eye score
Description	Blink estimation result	

●Expression estimation result

STB_FRAME_RESULT_EXPRESSION

Members	STB_INT32	Each expression estimation score
	anScore[STB_Expression_Max]	Positive/Negative degree
	STB_INT32 nDegree	
Description	Expression estimation result	

●Face recognition result

STB_FRAME_RESULT_RECOGNITION

Members	STB_INT32 nUID	User ID
	STB_INT32 nScore	Score
Description	Face recognition result	

●Stabilized face result

STB_FACE

Members	STB_INT32 nDetectID STB_INT32 nTrackingID STB_POS center STB_UINT32 nSize STB_INT32 conf STB_DIR direction STB_RES age STB_RES gender STB_GAZE gaze STB_BLINK blink STB_RES expression STB_RES recognition	Detecting ID Tracking ID Central coordinate Size Tracking confidence Stabilized face direction result Stabilized age result Stabilized gender result Stabilized gaze result Stabilized blink result Stabilized expression result Stabilized recognition result
Description	Stabilizes face detection result nDetectID allocates IDs on face detection result in order of storing. IDs are allocated from 0 to 34 and -1 for retry counting object. Therefore take it as an effective value when nDetectID allocated -1 as tracking is in process. nTrackingID allocates IDs on tracking objects in order starting from 0. Executing STB_ClearFrameResults() makes the ID back to 0. Those center, nSize, conf refer stabilized central coordinate, size and confidence.	

●Stabilized human body result

STB_BODY

Members	STB_INT32 nDetectID STB_INT32 nTrackingID STB_POS center STB_UINT32 nSize STB_INT32 conf	Detected ID Tracking ID Central coordinate Size Tracking confidence
Description	Stabilized human body result	

●Coordinate

STB_POS

Members	STB_UINT32 x STB_UINT32 y	X coordinate Y coordinate
Description	Coordinate	

●Stabilized blink result

STB_BLINK

Members	STB_STATUS status STB_INT32 ratioL STB_INT32 ratioR	Stabilization status Left eye score Right eye score
Description	Stabilized blink result Refer 2.5 Stabilization status for stabilization status.	

●Stabilized face direction result

STB_DIR

Members	STB_STATUS status STB_INT32 conf STB_INT32 yaw STB_INT32 pitch STB_INT32 roll	Stabilization status Stabilization confidence Up-down angle Left-right angle Rolling angle
Description	Stabilized face direction (Degree) result Refer 2.5 Stabilization status for stabilization status.	

●Stabilized gaze result

STB_GAZE

Members	STB_STATUS status STB_INT32 conf STB_INT32 UD STB_INT32 LR	Stabilization status Stabilization confidence Up-down angle Left-right angle
Description	Stabilized gaze(Degree)result Refer 2.5 Stabilization status for stabilization status.	

●Stabilized result

STB_RES

Members	STB_STATUS status STB_INT32 value STB_INT32 conf	Stabilization status Age/gender/expression /recognition stabilized result Stabilization confidence (This will be stabilization score in case of recognition)
Description	Stabilization result frame Refer 2.5 Stabilization status for stabilization status.	

2.8 Enum Type Definitions

●Expression Estimation

```
typedef enum {  
    STB_Expression_Neutral,  
    STB_Expression_Happiness,  
    STB_Expression_Surprise,  
    STB_Expression_Anger,  
    STB_Expression_Sadness,  
    STB_Expression_Max  
} STB_OKAO_EXPRESSION;
```

Definition	Description
STB_Expression_Neutral	Neutral
STB_Expression_Happiness	Happiness
STB_Expression_Surprise	Surprise
STB_Expression_Anger	Anger
STB_Expression_Sadness	Sadness

●Stabilization Expression Estimation

```
typedef enum {  
    STB_EX_UNKNOWN = -1,  
    STB_EX_NEUTRAL = 0,  
    STB_EX_HAPPINESS,  
    STB_EX_SURPRISE,  
    STB_EX_ANGER,  
    STB_EX_SADNESS,  
    STB_EX_MAX  
} STB_EXPRESSION;
```

Definition	Description
STB_EX_UNKNOWN	-1=Unknown
STB_EX_NEUTRAL	0=Neutral
STB_EX_HAPPINESS	Happiness
STB_EX_SURPRISE	Surprise
STB_EX_ANGER	Anger
STB_EX_SADNESS	Sadness

●Stabilization Status

```
typedef enum {  
    STB_STATUS_NO_DATA = -1,  
    STB_STATUS_CALCULATING = 0,  
    STB_STATUS_COMPLETE = 1,  
    STB_STATUS_FIXED = 2,  
    STB_STATUS_MAX;  
} STB_STATUS;
```

Definition	Description
STB_STATUS_NO_DATA	No data : No data of this person
STB_STATUS_CALCULATING	Calculating : Not enough data of this person -number of frames with object person
STB_STATUS_COMPLETE	Complete : Stabilization process completed
STB_STATUS_FIXED	Fixed : Stabilization result has fixed